

1 RLC CIRCUIT

The input voltage is $v_{in}(t)$, while the output voltage $v_o(t)$ is defined as the voltage across the LC-branch.

Assume $v_{in}(t) = 10\cos(\omega t)$ throughout the entire problem. $R = 1\ \Omega$ and $L = 1\text{ mH}$, while C is unknown.

We will first assume this circuit is used as a filter with input $v_{in}(t)$ and output $v_o(t)$, and $H(s) = \frac{V_o(s)}{V_{in}(s)}$

- a) What kind of filter does $H(s)$ represent? (lowpass, highpass, band-pass or band-stop)? Give reasons for your answer.

Answer: This is a band-stop filter since $|H(j\omega)|$ is 1 at low frequencies (the capacitor is blocking current) and $|H(j\omega)|$ is 1 at high frequencies (the inductor is blocking current). At the LC resonance frequency

$\omega = \frac{1}{\sqrt{LC}}$, the output is zero because the LC-branch is a short circuit.

- b) We want $v_o(t)$ to have as small amplitude as possible when the frequency is 250 Hz. Find the value of C that minimizes the amplitude of $v_o(t)$ at this frequency. What is the value of the minimum amplitude?

Answer: We want the filter to have the resonance frequency at 250 Hz, e.g.

$$\omega = \frac{1}{\sqrt{LC}} = 2\pi \cdot 250 \Rightarrow C = \frac{1}{L \cdot (2\pi \cdot 250)^2} = 405.3\ \mu\text{H}$$

We could also find this answer by looking at the transfer function $H(s) = \frac{sL + \frac{1}{sC}}{sL + \frac{1}{sC} + R}$ and find

$$H(j\omega) = \frac{j\omega L - j\frac{1}{\omega C}}{j\omega L - j\frac{1}{\omega C} + R}. \quad \text{The absolute values is } |H(j\omega)| = \frac{\omega L - \frac{1}{\omega C}}{\sqrt{R^2 + \left(\omega L - \frac{1}{\omega C}\right)^2}}$$

From this expression we get minimum amplitude when the numerator is zero, e.g. $\omega L = \frac{1}{\omega C}$

Assume now the frequency is 50 Hz. If you did not solve b), use $C = 1\text{ mF}$ in problems c) and d).

- c) How much active and reactive power is supplied from the voltage source? Is the circuit inductive or capacitive (give reasons for your answer)?

Answer: We find the total impedance seen from the source (at 50 Hz):

$$Z_{tot} = 1 + j2\pi \cdot 50 \cdot 10^{-3} + \frac{1}{j2\pi \cdot 50 \cdot 405.3 \cdot 10^{-6}} = 1 - j7.539 = 7.606e^{-j82.4^\circ}$$

The active and reactive power is then:

$$S = \frac{|V|^2}{Z_{tot}^*} = \frac{\left(\frac{10}{\sqrt{2}}\right)^2}{7.606e^{j82.4^\circ}} = 0.864 - j6.517$$

$$P = 0.864 \text{ W}$$

$$Q = -6.517 \text{ VAR}$$

Positive reactive power means capacitive. We can also claim the circuit is capacitive at this frequency since the impedance angle is negative.

Note that we divided the voltage by $\sqrt{2}$ to get the RMS value since 10 V is the peak magnitude of the cosine voltage source.

Using C=1 mF:

$$Z_{tot} = 1 + j2\pi \cdot 50 \cdot 10^{-3} + \frac{1}{j2\pi \cdot 50 \cdot 1 \cdot 10^{-3}} = 1 - j2.8689 = 3.0382e^{-j70.8^\circ}$$

The active and reactive power is then:

$$P = 5.417 \text{ W}$$

$$Q = -15.54 \text{ VAR}$$

Assume now we connect another resistor Z_{load} in parallel to the LC branch as shown in **Error! Reference source not found.**

d) Find the value of Z_{load} that maximizes the active power consumption in Z_{load} .

Answer: This can be solved in several ways. The simplest (but still quite challenging) method is to apply the maximum power transfer theorem and set the impedance Z_{load} equal to the conjugate of the equivalent Thevenin impedance Z_{th} seen from the terminals of Z_{load} . Z_{th} is found as the parallel

connection of R_1 with the series connection of L and C given by $X_{LC} = \omega L - \frac{1}{\omega C}$

$$Z_{th} = \frac{R_1 \cdot jX_{LC}}{R_1 + jX_{LC}} = \frac{R_1 X_{LC}^2 + jR_1^2 X_{LC}}{R_1^2 + X_{LC}^2} = \frac{R_1 X_{LC}^2}{R_1^2 + X_{LC}^2} + j \frac{R_1^2 X_{LC}}{R_1^2 + X_{LC}^2}$$

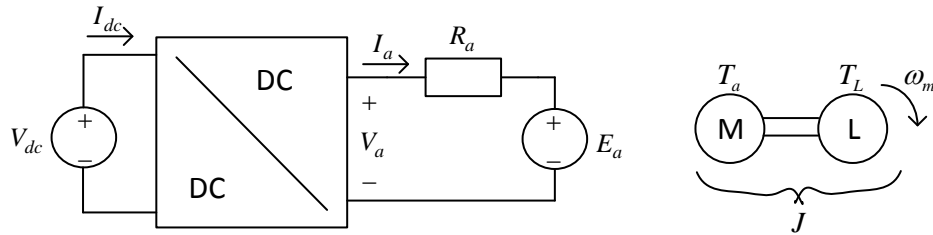
$$R_{th} = \frac{R_1 X_{LC}^2}{R_1^2 + X_{LC}^2}$$

$$X_{th} = \frac{R_1^2 X_{LC}}{R_1^2 + X_{LC}^2}$$

Consequently, $Z_{load} = Z_{th}^* = \frac{R_1 X_{LC}^2}{R_1^2 + X_{LC}^2} - j \frac{R_1^2 X_{LC}}{R_1^2 + X_{LC}^2}$ will maximize the active power consumption in Z_{load} .

With numerical values: $Z_{load} = 0.9827 - j0.1303$

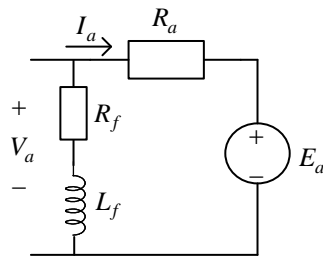
2 DC-MOTOR DRIVEN BY BATTERY AND DC/DC CONVERTER



The figure shows a battery with voltage V_{dc} connected to a DC-motor with resistance R_a and induced voltage E_a through a DC/DC-converter. The DC/DC-converter control system can set the required duty-cycle D defined as $D = \frac{V_a}{V_{dc}}$. The mechanical load has a load torque T_L .

- a) The field winding is not shown in the figure. Make a complete schematic of a shunt-excited DC-machine, including the field winding resistance R_f and field winding inductance L_f .

Answer: Shunt excited means that the field winding is supplied from the same voltage as the armature winding, i.e. they are connected in parallel (shunt). The schematic is as follows:



Assume in b) and c) that $T_L = k_L \omega_m$, where ω_m is the rotational speed of the shaft. The system has no mechanical gearbox. In problems b) and c), assume the motor operates in steady-state, i.e. no acceleration. Some useful formulas for the DC-motor is included in appendix.

Numerical values: $R_a = 0.1 \Omega$, $k\phi = 0.3 \frac{Vs}{rad}$, $k_L = 0.1 \frac{Nms}{rad}$ and $V_{dc} = 100 V$

- b) What duty-cycle is needed in order to have a shaft speed of $\omega_m = 200 \text{ rad/s}$?

Answer: As the motor operates in steady-state, we have $T_L = T_a \Rightarrow k\phi I_a = k_L \omega_m \Rightarrow I_a = \frac{0.1 \cdot 200}{0.3} = 66.67 \text{ A}$

The induced voltage is $E_a = 0.3 \cdot 200 = 60 \text{ V}$. The terminal voltage is then

$V_t = E_a + R_a I_a = 60 + 0.1 \cdot 66.67 = 66.67 \text{ V}$. Consequently, the duty cycle is $D = \frac{66.67}{100} = 0.667$

- c) Find an expression for the motor speed ω_m expressed by k_L, D, V_{dc}, k, R_a , as well as the motor constant k and the flux ϕ (these are the only variables in the desired expression)

Answer: We have the following equations:

$$V_a = DV_{dc} \quad , \quad V_a = R_a I_a + E_a \quad , \quad E_a = k\phi\omega_m \quad , \quad T_a = k\phi I_a \quad , \quad T_L = k_L\omega_m$$

We need to impose $T_a = T_L$

$$\text{Solving yields: } R_a I_a + k\phi\omega_m = DV_{dc} \quad , \quad I_a = \frac{k_L\omega_m}{k\phi}$$

$$R_a \frac{k_L\omega_m}{k\phi} + k\phi\omega_m = DV_{dc} \quad \text{and we get } \omega_m = \frac{DV_{dc}}{k\phi + \frac{R_a k_L}{k\phi}}$$

Assume now that the load torque is zero, $T_L = 0$. Assume also the system has a total moment of inertia equal to J . At $t = 0$, the DC/DC-converter makes a step in duty cycle from $D = 0$ to $D = D_0$.

d) Find the expression for the motor speed $\omega_m(t)$ for $t \geq 0$ (only variables, no numerical values).

Answer: We want to solve this with Laplace transform (can also use differential equations)

We need to add the equation for angular acceleration:

$$sJ\omega_m = T_a - T_L, \quad \text{with } T_L = 0 \quad \text{we get } sJ\omega_m = k\phi I_a$$

$$\text{Circuit equation: } V_a = R_a I_a + E_a \Rightarrow DV_{dc} = R_a \frac{sJ\omega_m}{k\phi} + k\phi\omega_m$$

We find the transfer function from Duty cycle D to speed ω_m :

$$H(s) = \frac{\omega_m(s)}{D(s)} = \frac{V_{dc}}{s \frac{R_a J}{k\phi} + k\phi} = \frac{V_{dc} k\phi}{R_a J} \frac{1}{s + \frac{(k\phi)^2}{R_a J}} = K \frac{1}{s + a}$$

Where $K = \frac{V_{dc} k\phi}{R_a J}$, $a = \frac{(k\phi)^2}{R_a J}$ is introduced for simpler expressions.

We are making a step in duty cycle, hence $D(s) = \frac{D_0}{s}$. This gives the following expression for speed:

$$\omega_m(s) = KD_0 \frac{1}{s+a} \frac{1}{s}$$

$$\text{Performing partial fraction expansion yields: } \omega_m(s) = KD_0 \frac{1}{s+a} \frac{1}{s} = \frac{KD_0}{a} \left(\frac{1}{s} - \frac{1}{s+a} \right)$$

And we can make the inverse transform:

$$\omega_m(t) = \frac{KD_0}{a} (1 - e^{-at}) = \frac{V_{dc}}{k\phi} D_0 \left(1 - e^{-\frac{(k\phi)^2}{R_a J} t} \right)$$

3 CIRCUIT CALCULATIONS INCLUDING IRON CORE

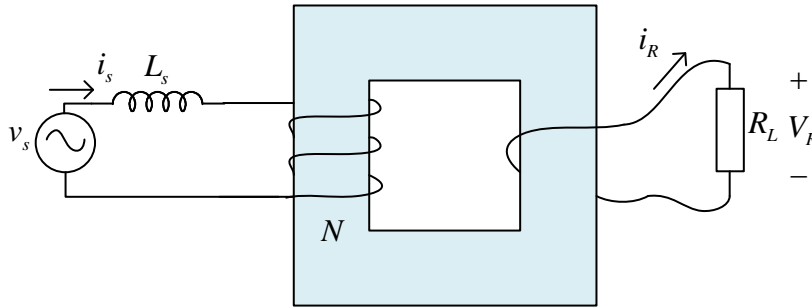


Figure 1 – Voltage source, iron core and load resistance

A resistor is connected to a voltage source through an iron core as presented in Figure 1. The core has $N = 3$ windings on the voltage source side, and a single winding at the load resistor side. We make the following assumptions:

- All induced magnetic field is kept within the core
- The iron is ideal, i.e. $\mu_r = \infty$
- The core will not saturate

a) Explain why we can treat the iron core as an ideal transformer with ratio N .

NB: This problem is withdrawn from the exam judgement as it is not clear how to answer it. In some way, the answer is given in the problem text.

b) If i_s is positive, is i_R positive or negative? Explain why.

NB: This problem is withdrawn from the exam judgement as it cannot be solved. It is the flux derivative that determines the direction of i_R , and the derivative cannot be identified only based on the sign of the primary current.

If the frequency is $f = 50 \text{ Hz}$, $v_s = 10 \text{ V (RMS)}$ and $R_L = 0.5 \Omega$, the current i_s has an RMS-value of 2 A .

c) Find the numerical value of the inductor L

Answer: This can be solved in several ways. We choose to find the total impedance seen from the voltage source. This is given by $Z_{tot} = j\omega L + \frac{R_L}{N^2}$. The fact that we need to divide by the turns number squared can be derived or remembered from the assignments.

We can find an expression for the source current i_s :

$$i_s = \frac{v_s}{j\omega L + N^2 R_L}$$

The absolute value (RMS) is $|i_s| = \frac{v_s}{\sqrt{(\omega L)^2 + (N^2 R_L)^2}}$

Setting this equal to 2 A yields:

$$2 = \frac{10}{\sqrt{(\omega L)^2 + (9 \cdot 0.5)^2}} \Rightarrow 25 = (\omega L)^2 + 20.25 \Rightarrow L = \frac{\sqrt{4.75}}{2 \cdot \pi \cdot 50} = 6.94 \text{ mH}$$

- d) Derive an expression for the power consumed by the resistor R_L . No numerical values, only with symbols (v_s, L_s, N, R_L, f)

Answer: We already have the expression for the source current found above. We can then easily find the current through the resistor as:

$$i_R = \frac{N v_s}{j\omega L + N^2 R_L}$$

The active power through the resistor can be found as $P_{load} = |I_R|^2 R_L$

This is equal to

$$P_{load} = \frac{(N v_s)^2 R_L}{(\omega L)^2 + (N^2 R_L)^2} = \frac{(N v_s)^2 R_L}{(2\pi f L)^2 + (N^2 R_L)^2}$$

This expression can be found also by other approaches, and all expressions that are equivalent will get full score.

4 DIODE RECTIFIER

Figure 1 shows a diode rectifier where the AC-voltage is a triangular wave. In problem a) and b), the DC-side is a constant current source I_{dc} , while in problem c) and d) it is represented by a resistor R .

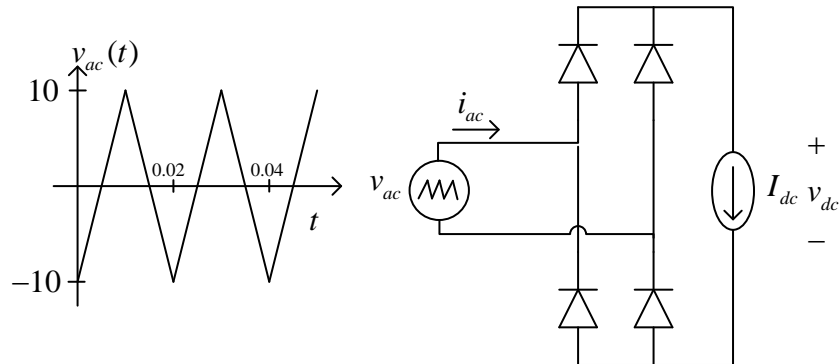


Figure 2: Diode rectifier supplied by a triangular voltage source. Constant DC-current

Assume $I_{dc} = 5 A$

a) Find and sketch the DC-side voltage $v_{dc}(t)$ and the AC-side current $i_{ac}(t)$ for $0 \leq t \leq 0.04 s$.

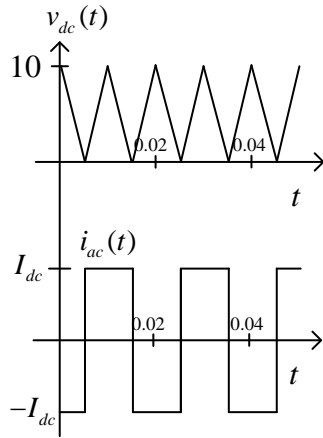
Answer: Similar to when a sinusoidal AC-voltage is applied (see the assignment), the DC-voltage is the absolute value of the AC-voltage $v_{dc}(t) = \text{abs}(v_{ac}(t))$

We can find the ac-current in several ways. One method is to set the instantaneous power equal on both sides: $P_{ac}(t) = v_{ac}(t)i_{ac}(t) = P_{dc}(t) = I_{dc}v_{dc}(t)$

This gives: $i_{ac} = I_{dc} \frac{v_{dc}(t)}{v_{ac}(t)}$.

The ratio between dc- and ac voltage is either +1 or -1, and is equal to the sign of the ac-voltage. We can express this mathematically as $i_{ac}(t) = I_{dc} \text{sgn}(v_{ac}(t))$.

We can plot both functions as:



b) What is the average power delivered from the AC voltage source?

Answer: We can find this from either the dc- or the ac-side (power is equal on both sides). Here we choose the dc-side since the current is constant there. The average power is then equal to the dc-current times the average dc-voltage.

$$P = I_{dc} \cdot \frac{10}{2} = 5 \cdot 5 = 25 \text{ W}$$

Here we have used that the average of a triangular wave is the peak-to-peak value divided by two.

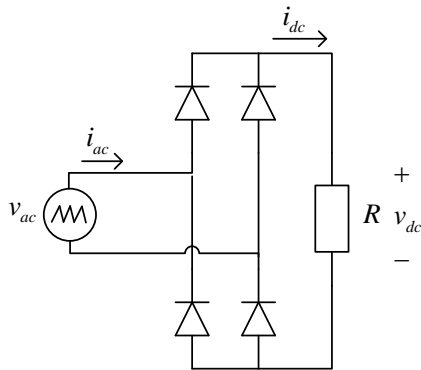


Figure 3 - Diode rectifier supplied by a triangular voltage source. Resistive DC-load

Now the constant current source is replaced with a resistor $R = 2 \Omega$ as shown in Figure 2.

c) Find and sketch the DC-side current $i_{dc}(t)$ and AC-side current $i_{ac}(t)$ for $0 \leq t \leq 0.04 \text{ s}$.

The dc-voltage is the same as before: $v_{dc}(t) = \text{abs}(v_{ac}(t))$, hence the dc-current is found as

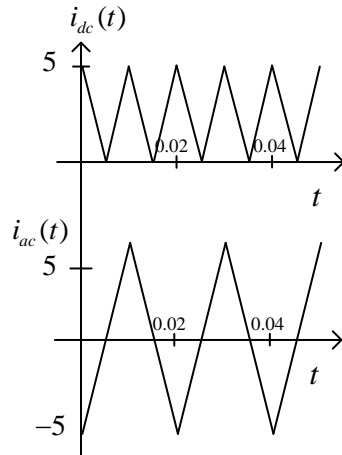
$$i_{dc}(t) = \frac{v_{dc}(t)}{R} = \frac{\text{abs}(v_{ac}(t))}{R}$$

We find the ac-current by setting dc- and ac-instantaneous power equal:

$$v_{ac}(t)i_{ac}(t) = v_{dc}(t)i_{dc}(t)$$

$$i_{ac}(t) = \frac{v_{dc}(t)i_{dc}(t)}{v_{ac}(t)} = i_{dc}(t) \cdot \text{sgn}(v_{ac}(t))$$

Hence, the general expression is the same as before. We can now plot both functions:



d) What is the average power delivered from the AC voltage source?

Answer: We find the time-domain expression for instantaneous power as:

$$\begin{aligned} v_{ac}(t)i_{ac}(t) &= v_{ac}(t)i_{dc}(t) \cdot \text{sgn}(v_{ac}(t)) = \text{abs}(v_{ac}(t)) \cdot i_{dc}(t) = \text{abs}(v_{ac}(t)) \frac{\text{abs}(v_{ac}(t))}{R} \\ &= \frac{\text{abs}(v_{ac}(t))^2}{R} \end{aligned}$$

Since the instantaneous power is a triangular wave multiplied with itself, we could use the RMS value of a triangular wave and multiply it with itself to get the average value. By using the RMS definition we can show that the RMS-value of a triangular wave is $\frac{V_p}{\sqrt{3}}$, where V_p is the peak value.

Then, we can find that the average power is:

$$P = \frac{\left(\frac{10}{\sqrt{3}}\right)^2}{R} = \frac{100}{6} = 16.667 \text{ W}$$

We could also find this number in different ways, e.g. by finding the actual time-domain expression for $v_{ac}(t)$, multiplying it with itself, and integrate over a period to find the average.