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NORWEGIAN UNIVERSITY OF SCIENCE AND TECHNOLOGY DEPARTMENT OF ELECTRONICS AND TELECOMMUNICATIONS

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### EXAMINATION IN COURSE TTT4120 DIGITAL SIGNAL PROCESSING

Date: Thursday, 19 August 2010 Time: 15.00 - 19.00

Permitted aids: D–No printed or hand-written material allowed. Specified, simple calculator allowed.

#### INFORMATION

- The examination consists of 4 problems:
  - Problem 1 concerns analysis of digital filters.
  - Problem 2 concerns finite word length effects in filter structures.
  - Problem 3 concerns stocastical processes.
  - Problem 4 concerns sampling in frequency domain and DFT.

The weight of each subproblem is given in parenthesis. Total number of points is 56.

- The solution steps should be evident and all answers should be justified!
- Some important formulae can be found in the appendix.
- The teacher will go around twice, around 16.00 and around 17.45.
- Grades will be announced by September 9th.

# Good luck!

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#### Problem 1 (3+6+9+4=22 points)

A discrete-time system with transfer function H(z) consists of two subsystems connected in series. The first subsystem is anticausal and is given by its transfer function

$$H_1(z) = \frac{1}{1 - 3z^{-1}}.$$

The second subsystem is causal and is given by the following difference equation

$$2y(n) - y(n-1) = x(n) - 2x(n-1),$$

where x(n) and y(n) are the input and the output signal of the subsystem, respectively.

- 1a) Sketch the region of convergency (ROC) for the transfer functions of the subsystems  $H_1(z)$  and  $H_2(z)$ , and their serial connection H(z).
- 1b) Show that the unit pulse responses of the two subsystems are given by

$$h_1(n) = \begin{cases} -3^n & n < 0\\ 0 & n \ge 0 \end{cases}$$
$$h_2(n) = \begin{cases} 0 & n < 0\\ \frac{1}{2} & n = 0\\ -3\left(\frac{1}{2}\right)^{n+1} & n > 0, \end{cases}$$

and that the unit pulse response of the entire system is given by

$$h(n) = \begin{cases} -\frac{3^n}{5} & n < 0\\ \frac{3}{5} \left(\frac{1}{2}\right)^{n+1} & n \ge 0. \end{cases}$$

1c) Find out whether the two subsystems and their serial connection are stable? Are they FIR- or IIR systems? Do they have a linear phase response? Determine their type (lowpass, highpass, bandpass, bandstop or all-pass).

1d) Draw the direct form II structure of the subsystem  $H_2(z)$ . Draw the cascade structure of the entire system H(z).

## Problem 2 (2+3+4+4=13 points)

Figure 1 shows the parallel structure of the filter H(z) from Problem 1.

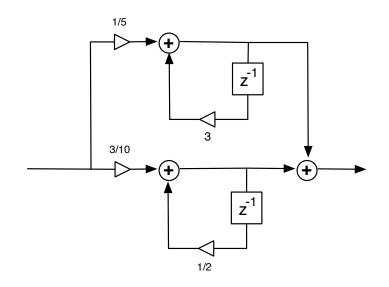


Figure 1: Implementation of a digital filter

All internal and external signals in the filter structure are represented by binary fixedcomma representation with 4 bits and the dynamic range [-1, 1). Rounding is performed after each multiplication. Assume that the rounding error can be considered as uniformly distributed white noise.

- 2a) Derive an expression for rounding error power  $\sigma_e^2$  after a multiplication. Find also the value of  $\sigma_e^2$ .
- **2b)** Show that the signal power at the output of an LTI filter with unit sample response g(n) is equal to

$$\sigma_q^2 = \sigma_e^2 \, r_{gg}(0)$$

when white noise e(n) with power  $\sigma_e^2$  is sent at the input.

- 2c) Find the total rounding error power at the output of the filter in Figure 1.
- **2d)** Find the necessary scaling factor at the input of the filter in Figure 1 in order to avoid overflow.

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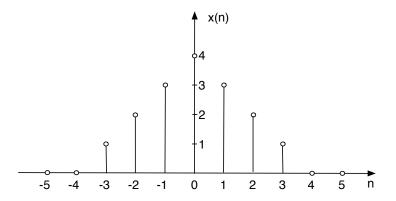
## Problem 3 (1+4+5+2=12 points)

A stocastical process x(n) is generated by sending white Gaussian noise w(n) with varianse  $\sigma_w^2 = 1$  through a system with transfer function  $H(z) = 1 - 2z^{-1}$ .

- **3a)** Which type of prosess is x(n)?
- **3b)** Find the autocorrelation function  $\gamma_{xx}(l)$  and the power spectral density  $\Gamma_{xx}(\omega)$  of the process.
- **3c)** We wish to model the process by an optimal AR(2) model. Find the model parameters
- **3d)** Find an expression for the power spectral density estimator  $\hat{\Gamma}_{xx}(\omega)$  based on the optimal AR(2) model.

### Problem 4 (2+4+3=9 points)

A discrete-time signal x(n) is given by the following figure.



- **4a)** Find the spectrum  $X(\omega)$  of the signal x(n).
- **4b)** We take samples of the spectrum  $X(\omega)$  in the following way

$$X(k) = X(\omega)|_{\omega = \frac{2\pi k}{N}}.$$

Sketch the signal y(n) which has spectrum given by X(k).

How do we have to chose N in order to be able to recover the signal x(n) from the spectral samples X(k)?

4c) Explain the principle of the overlap-add method for filtering very long sequences through an FIR filter using DFT.