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CLASSIFICATION SYSTEM FOR REPORTING EVENTS INVOLVING HUMAN MALFUNCTIONS

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<u>Abstract</u>. The report describes a set of categories for reporting industrial incidents and events involving human malfunction. The classification system aims at ensuring information adequate for improvement of human work situations and man-machine interface systems and for attempts to quantify "human error" rates. The classification system has a multifacetted non-hierarchical structure and its compatibility with Ispra's ERDS classification is described. The collection of the information in general and for quantification purposes are discussed. 24 categories, 12 of which being human factors oriented, are listed with their respective subcategories, and comments are given.

Underlying models of human data processes and their typical malfunctions and of a human decision sequence are described.

7 references.

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March 1981 Risø National Laboratory, DK 4000 Roskilde, Denmark. <u>INIS-descriptors</u>. BEHAVIOUR; DATA ACQUISITION; ERRORS; FAILURE MODE ANALYSIS; HUMAN FACTORS; INDUSTRIAL ACCIDENTS; NUCLEAR POWER PLANTS; PERSONNEL; TAXONOMY; WORK

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INTRODUCTION

The present note is prepared to support a discussion on a set of categories which can be used in industrial incident and event reports to ensure collection of adequate information for improvement of human work situations and man-machine interface systems as well as for attempts to quantify "human error" rates.

Discussion of taxonomies to describe human tasks, performance and errors seems to be an everlasting activity among human factors specialists and the field is not very attractive after several not too successful attempts. However, if one wishes to quantify human errors, one has to identify and define the items one wants to count or measure and unless the development of modern man--machine interfaces should be controlled by piecemeal remedies after spectacular man-machine misfits - such as e.g. TMI - it is necessary to use models of human performance and define categories of problems. The basic issue is, probably, that one has to accept that the structure and members of a proper taxonomy depend very much on the intended use and the specific aspects of the work situation. One important presert aspect is the rapid change in level of automation and in design of interface caused by modern information technology. Consequently, human work situation changes and the taxonomy used must be helpful for transfer of empirical data to new task designs.

The structure of the taxonomy

To be able to quantify the frequency of inappropriate human acts in a meaningful way, it is necessary to separate cases of intrinsic human variability and spontaneous human errors from cases of psychologically normal human reactions to external events or changes in the work situation. This means that a simple classification of human errors with reference to the task sequence in terms of omission, commission, timing errors etc. is not adequate. Careful efforts should be spent to identify potential external causes with reference to categories which allow estimates of frequencies in another particular situation. To serve as a basis for more error tolerant task and equipment design, more fundamental understanding of human malfunction in industrial work situations is needed. Event reports are an extremely valuable data source for such research, but for this purpose it 's important to use a taxonomy which serve to represent the circumstances preceding and succeeding the event of human malfunction and the relation to the human task, and maintain this information in the data recorded. This leads to a multifacetted description of the human involvement in system failures as shown in Figure 1, rather than a classical, heirarchical and exclusive classification system.

The structure of this taxonomy is more important than the detailed classes related to the different facets. Some of these will depend on the specific system in question; others are preliminary classes which should be refined by future data collection and analysis. Therefore, free text comments and descriptions in the reports are necessary and the facets used in the present taxonomy can serve to indicate the type of information needed.

Emphasis has been given to obtain compatibility between the human malfunction taxonomy and the taxonomy of the European Reliability Data System under development at ISPRA (Mancini et al. 1979). The combination of the taxonomies is described in the following.

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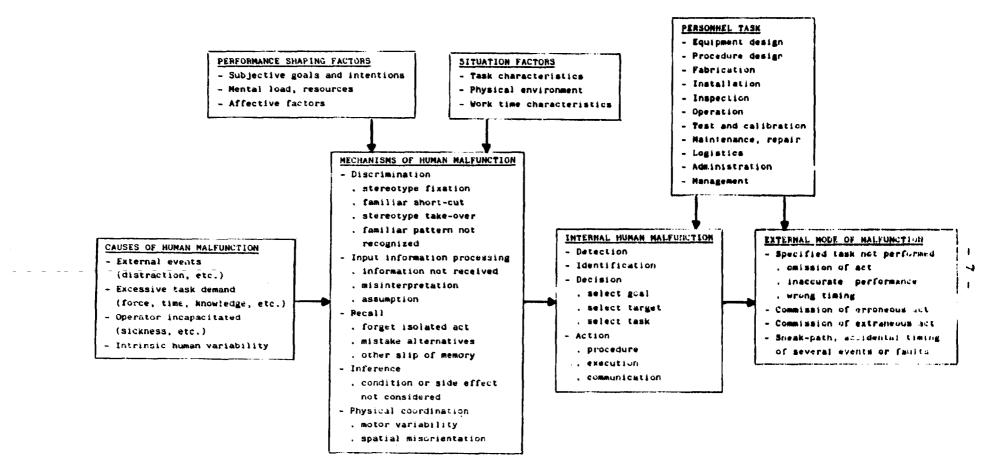


Figure 1. Multifacetted taxonomy for description and analysis of events involving human malfunction.

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Collection of data, general

The means of data collection are tightly coupled to the taxonomy and its purpose: They should together constitute a good compromise between the following requirements:

- The reporting procedure should not be too difficult or require special insight (e.g. in human factors) in excess of what is reasonable from the people involved in reporting.
- The information reported should be covering and unambiguous with respect to its intended use.

It is foreseen that a good compromise can be developed only by an iterative process: the experiences from the practical event reporting and use of the information collected can be expected to lead to changes of both the reporting procedure and the taxonomy.

The above will be discussed more detailed in the following, referring to Figure 2, where the categories of the taxonomy are related to their use for event reporting and for analysis.

In order to facilitate event recording, preprinted forms will be used for categories, where reporting can be done in-plant by filling in such forms like checklists. At the outset the following categories are considered suitable for this kind of reporting:

- PLANT: PLANT IDENTIFICATION DATA SYSTEM IDENTIFICATION
- EVENT ANALYSIS: EVENT DETECTION PLANT STATE SYSTEMS AND COMPONENTS AFFECTED CONSEQUENCES OF THE EVENT RECOVERY SITUATION
- COMPONENT RELIABILITY DATA SYSTEM: MODES OF FAILURE CAUSES OF FAILURE ACTIONS TAKEN
- HUMAN SYSTEM: PERSONNEL IDENTIFICATION PERSONNEL LOCATION

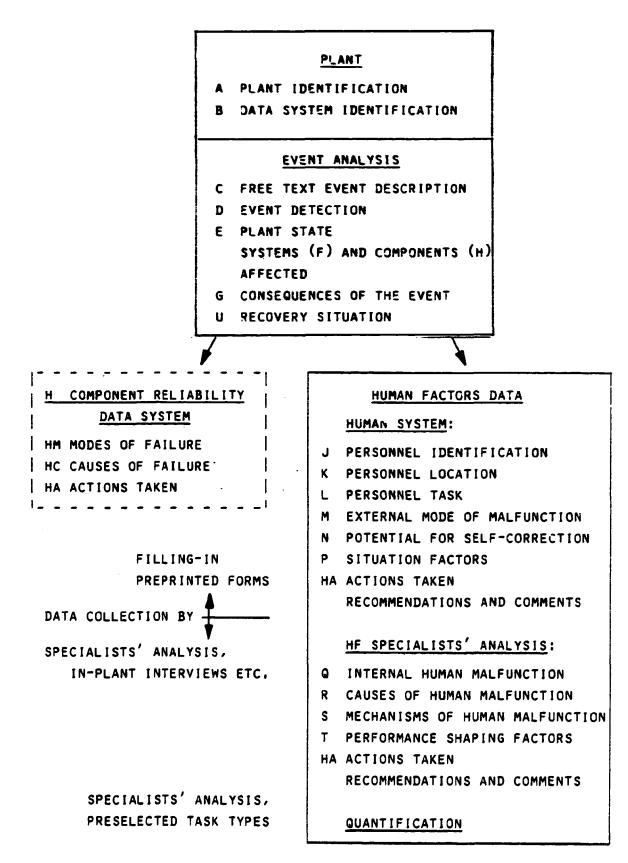


Figure 2: Use of human malfunction taxonomy.

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PERSONNEL TASK EXTERNAL MODE OF MALFUNCTION POTENTIAL FOR SELF-CORRECTION SITUATION FACTORS ACTIONS TAKEN

The preprinted forms and examples of their use are presented in the document SINDOC (81)15.

FREE TEXT EVENT DESCRIPTION is intended for a short general description, abt. 10 lines of text.

The category U: RECOVERY SITUATION has been reserved for the purpose of characterizing the short term remedies applied in order to cope with a particular event. This category should be distinguished from categories HA: COMPONENTS: ACTIONS TAKEN and HA: ACTIONS TAKEN describing the long term remedies applied.

RECOVERY SITUATION has not yet been provided with subcategories and will not be discussed further in this report.

The categories SYSTEMS AND COMPONENTS AFFECTED are intended for characterization of both technical failures and human malfunctions. In case of a technical failure the classification thereafter will continue in the COMPONENT RELIABILITY DATA SYSTEM indicated by H in figure 2, specifying MODES and CAUSES CF FAILURE and ACTIONS TAKEN. In case of a human malfunction, SYSTEMS AND COM-PONENTS AFFECTED will specify the physical contact/interface between the technical system and the human activity, as explained later in the comments given to this category.

The RECOMMENDATIONS AND COMMENTS under HUMAN FACTORS DATA are intended for supplementary information for the categories under HUMAN SYSTEM and, particularly, for supporting the more subtle classification under the categories:

- HF SPECIALISTS' ANALYSIS: INTERNAL HUMAN MALFUNCTION CAUSES OF HUMAN MALFUNCTION MECHANISMS OF HUMAN MALFUNCTION PERFORMANCE SHAPING FACTORS ACTIONS TAKEN

The classification of these categories is considered to need human factors specialists' analysis, at least in the beginning, and also will involve e.g. in-plant interviews.

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As indicated in Figure 2, the categories under PLANT and EVENT ANALYSIS are expected to be common to the component reliabili*y data system under development at ISPRA (Mancini et al. 1979) and the taxonomy discussed in this report.

In case of events involving several subevents, e.g. component failure and human malfunction or several human malfunctions, the free text description and the three categories A, B and D could be common to the subevents, these being thereafter classified as independent events.

Collection of data for quantification

When data collection is planned for quantification of human error rates special categories of information must be derived from task analysis.

- "Denominator" information must be found, i.e. the frequency of opportunity for the relevant categories of human malfunction. For some spontaneous human errors this frequency is related to the task frequency; for malfunctions with external causes the relation to task frequency is more complex and the task frequency can only be used as denominator for estimation of error rates in work situations very similar to those of the plant serving as data source.
- Recovery factors: for use in quantification of human malfunction, features of the work situation related to the potential for detection of errors by the person himself is very important and should be emphasized in the task analysis aiming at denominators.

A PLANT IDENTIFICATION

- A1 Power reactors:
- A1.1 BWR
- A1.2 PWR
- A1.3 Gascooled reactors, AGR, Magnox
- A1.4 Fast breeder reactors
- A1.5 Heavy water reactors
- A2 Research reactors
- A3 Other. Fuel manufacturing and reprocessing, transport etc.

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Comments

In a data retrieval system extended to more industrial branches than that of nuclear power, the specific branches could be typified according to existing proven indexing systems.

B DATA SYSTEM IDENTIFICATION

Comments

The content of this category, having not yet been worked out in details, should include descriptors characterizing items such as:

- Identification code for the data system in relation to other corresponding data systems.
- Whether or not the event is comprising several subevents.
- Individual code numbers for the reported event and subevents, if any, also covering follow--up or supplementary information reported after the preliminary event report.
- Date of event occurrence and date of report.
- Individual code number for the power station unit (reactor) involved.

- D EVENT DETECTION
- D1 Announced by automatic alarm
- D2 During maintenance:
- D2.1 Planned/preventive
- D2.2 Repair/modification
- D3 During test or special inspection
- D4 <u>During operational activities</u> (excluding automatic alarm announcing):
- D4.1 Preparatory activities
- D4.2 When calling system into operation
- D4.3 Routine surveillance during operation
- D4.4 Other not covered above
- D5 During management activities:
- D5.1 Review of log, recorder charts
- D5.2 Other
- D6 <u>Malfunction "seen, found"</u> without further specification
- D7 <u>Not stated, not applicable</u>

Comments

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Event detection, i.e. information regarding the way the abnormality was detected, is important to judge the role and quality of the various measures to monitor the operational state of the system. The information also makes it possible to estimate the time interval from different categories of technical faults and inappropriate human acts to their detection.

E	PLANT STATE
E1	Under construction
E2	Preoperational, startup or power ascension tests (in progress)
EЗ	Routine startup operations
E4	Routine shutdown operations
E5	Steady state operation
E6	Stretch-out operation
E7	Load changes during routine power operation
E8	Shutdown (hot or cold) except refueling
E9	Refueling
E10	Other (including special tests, emergency shutdown operations, etc.)
E11	Not applicable, not stated

Comments

The plant state should refer to the occurrence of the malfunction. (The recognition of the malfunction is classified under the category: EVENT DETECTION).

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SYSTEMS (F) AND COMPONENTS (H) AFFECTED

F Systems

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FA - NUCLEAR HEAT SYSTEM
FA1 - Reactor Core System
FA2 - Reactor Vessel Equipment
FA3 - Primary Coolant System (PWR)
FA4 - Pressurizing System (PWR)
FA5 - Steam Generator System (PWR)
FA6 - Recirculating Water System (BWR)
FA7 - Coolect System (BWR)
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- FA7 Coolant System (BWR)
- FA8 Control Rod System (PWR)
- FA9 Control Rod System (BWR)

FB - ENGNEERED SAFETY FEATURES

FB1 - Reactor Containment System (FWR) FB2 - Reactor Containment System (BWR) FB3 - Containment Spray System FB4 - Containment Isolation System FB5 - Containment Pressure Suppression System (BWR) FBo - Pressure Relief System (PWR) FD7 - Hydrogen Venting System FD8 - Post-Accident Containment Atmosphere Mixing System F39 - Containment Gas Control system FB10 - Auxiliary Feedwater System (PWR) FB11 - Reactor Core Isolation Cooling System (BWR) F312 - Emergency Boration System (PWR) FB13 - Stand-by Liquid Control System (SWR) FB14 - Residual Heat Removal System (PWR) FB15 - Residual Heat Removal System (BWR) FB16 - High Pressure Coolant Injection System (PWR) FB17 - Accumulation System (PWR) FB13 - Low Pressure Coolant Injection System (PWR) FB19 - Nuclear Boiler Overpressure Protection System (BWR) F320 - High Pressure Core Spray System (BWR) F321 - High Pressure Coolant Injection System (BWR) FB22 - Low Pressure Core Spray System (BWR) F323 - Low Pressure Coolant Injection System (BWR)

F C - REACTOR AUXILIARY SYSTEM

- FC1 Chemical and Volume Control System (FWR)
- FC2 Reactor Water Cleanup System (BWR)
- FC3 Boron Recovery System (PWR)
- FC4 Reactor Treated Water Storage System (PWR)

FC5 - Primary Component Cooling Water System

FC6 - Control Rod Drive Cooling Water System (PWR)

EC7 - Primary Loads Service Water System

FC8 - Ultimate Heat Sink System

FC9 - Refueling Water System

FC10 - Reactor Water Storage System (BWR)

FC11 - Radwasta Cooling Water System

FC12 - Safety Equipment Compressed Air System

FC13 - Nuclear System Fire Protection System

FC14 - Hydrogen, Oxygen, Nitrogen Gas Distribution System

FC15 - Nuclear System Building Servicing Equipment

FD - FUEL STORAGE AND HANDLING SYSTEM

FD1 - Fuel Storage and Handling Equipment

FD2 - Spent Fuel Pool Cooling and Cleanup System

FD3 - Containment Pool Cooling and Cleanup System (BWR)

FE - RADIOACTIVE WASTE MANAGEMENT SYSTEM

FE1 - Liquid Radwaste System

FE2 - Solid Radwaste System

FE3 - Gaseous Radwaste System (PWR)

FE4 - Gaseous Radwaste System (BWR)

FE5 - Equipment and Floor Drainage System

FE6 - Recovered Water Storage and Distribution System

FE7 - Stear Generator Blowdown System (PWR)

FF - STEAM AND FOWER CONVERSION SYSTEM

FFI - Main Steam System

FF2 - Turbine System

FF3 Turbine Steam Scaling System

FF4 - Main Condenser System

EF5 - Non-Condentable Gases Extension System

FF6 - Turbine Bypass System

FF7 - Steam Extraction System

FF8 - Condensate and Feedwater System

FF9 - Moisture Separators, Reheaters System

FF10 - Moisture Separators, Reheaters Drain System

FF11 - Heaters Drain and Vents System

FF12 - Various Thermal Cycle Drains and Vents System

FF13 - Chemical Additive Injection System

FE14 - Condensate Demineralizer System

FF15 - Circulating Water System (open cycle)

FF10 - Circulating Water System (closed cycle)

FF17 - Circulating Water Treatment System

FF18 - Cooling Towers System

F G - POWER TRANSMISSION SYSTEM

- ...FGl Generator System
 - FG2 Main Bus Duct System
 - FG3 Main Transformers System
 - FG4 Auxiliary Transformers System
 - FG5 Back-up Auxiliary Transformers System
 - FG6 Switchyard to Station H. V. Connection

FH - ELECTRIC POWER SYSTEM

- FHI Medium Voltage System
- FH2 Low Voltage System
- FH3 Vital Instrument and Computer A.C. System
- FH4 On-Site D.C. System
- FH5 Diesel Generator System
- FH6 Electrical Heat Tracing System
- FH7 Mighting and Taxed Motive Power System
- FH3 Security System
- F²³ Communication System
- FH10 Cathodic Protection System
- FH11 Grounding System

FI - INSTRUMENTATION, SUPERVISION, MONITORING SYSTEM

- FIL Computer System
- FI2 System
- F13 Main Control Room Benchboards System
- FI4 In-Core and Ex-Core Neutron Monitoring System
- F15 Radiation Monitoring System
- F16 Reactor Coolant Pressure Boundary Leak Detection System
- FI7 Containment Leak Detection System
- FIS Failed Fuel Detection System (PWR)
- FI9 Main Steam Line Radiation Monitoring System (BWR)
- FIIO Hydrogen Monitoring System (BWR)
- FILL Off-Site Radiological Monitoring System
- FI12 Seismic Monitoring System
- FIL3 Meteorological Monitoring System
- FI14 Sampling System
- FIL5 Perturbographic System
- F16 Cooling Water Temperature Monitoring System

FL - PROTECTION AND CONTROL SYSTEM

- FL1 Reactor Protection System
- FL2 BOP Protection System
- FL3 Engineered Safety Features Actuation System
- FL4 Reactor Power Control System (FWR)
- FL3 Reactor Power Control System (BWR)

- FL6 Recirculation Flow Control System (BWR)
- FL7 Feedwater Control System (3WR)
- ELS Pressure Regulator System (BWR)
- FL9 Turbine Control System
- FL10 Remote Shutdown System
- FL11 Remote Control Logic System

FM - PLANT BUILDINGS HVAC SYSTEM

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FM1 - Containment Recirculation Air Cooling System
FM2 - Containment Air Purification and Cleanup System (PWR)
FM3 - Drywell Recirculation Air Cooling System (BWR)
FM4 - Containment Purge System
FM5 - Containment Low Purge and Pressure Control System (BWR)
FM6 - Drywell Purge System (BWR)
FM7 - Containment Pressure Relief System (PWR)
FMS - Anulus Recirculation and Exhaust System
FM9 - In-Core Instrumentation Purge System
FM10 - Control Rod Drive Mechanism Cooling System (PWR)
FMII - Reactor Auxiliary Building HVAC System
FM12 - Control Room Building HVAC System
FM13 - Fuel Building HVAC System
FM14 - Emergency Diesel Generator Building HVAC System
FM15 - Radwaste Building HVAC System
FM16 - Solid Waste Storage HVAC System
FM17 - ESF Vaults HVAC System
FM18 - Controlled Area Service Building HVAC System
FM19 - Ultimate Sink Structure HVAC System
FM20 - Main Pipe Chase HVAC System
FM21 - Interbuildings Corridors and Tunnels HVAC System
FM22 - Auxiliary Feedwater Pumps Chase HVAC System (PWR)
FM23 - Plant Stack and Vent Air Discharge System
FM24 - Turbine Building HVAC System (PWR)
FM25 - Turbine Building HVAC System (BWR)
FM26 - Non-Essential Switchgear Building HVAC System
FM27 - General Service Building HVAC System
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FN - SERVICE AUXILIARY SYSTEM

FNL	- Service Water System
FN2	- BOP Cooling Water System
FN3	- Chilled Water System
FN4	- Demineralized Water Production and Distribution System
	- Raw Water Make-up System
FN6	- Pretreated Water Distribution System
FN7	- Potable and Sanitary Water System
FNð	- Auxiliary Steam and Hot Water System
FN9	- Auxiliary Boiler
EN10	- Non-Radioactive Waste Treatment System

FN11 - Service and Instrument Compressed Air System FN12 - BOP Sampling System FN13 - Industrial Water System FN14 - Diaphragm Bailing System

FN15 - BOP Fire Fighting System

FN16 - Service Equipment System

FO - STRUCTURAL SYSTEMS

FOI - Reactor Auxiliary Building

- FO2 Fuel Storage Building
- FO3 Turbine, Condensate Treatment and Heater Bay Building
- FC4 ESF Vaults
- FO5 Radwaste Treatment Building and Tank Farm
- FO6 Solid Waste Storage Structure
- FOT Control Room Building
- FOS Emergency Diesel Generator Buildings and Diesel Generator Fuel Storage
- F.O. Ultimate Heat Sink Structure
- FO10 Controlled Area Service Building
- FOLL Circulating Water Structure
- FO12 Miscellaneous Shared Buildings and Structure.

H Components

H1 ANNUCIATOR MCDULES

- H1A Audio
- H1B Visual
- H1C Audio/Visual

H2 MECHANICAL FUNCTION UNITS

- H2A Controller/Governor
- H2B Coupling
- H2C Power Transmission Device

H3 PENETRATIONS, PRIMARY CONTAINMENT

- H3A Personnel Access
- H3B Fuel Handling
- H3C Equipment Access
- H3D Electrical
- H3E Instrument Line
- H3F Process Piping

		- 21 -	CINCUITE CI COD /INFEDDUETEDC
ца Р 1	COMBINERS	H11	<u>CIRCUIT CICSER/INTERRUPTERS</u>
		H11A	Circuit Breaker
H4A	Flare	H11A H11B	Contractor
H4B	Catalytic	H11C	Controller
H4C	Thermal	H11D	Starter
		H11E	Switch
• H5 RE	STAYS	H11F	Switchgear
			SATCUREN
н6 <u>s</u> н	ICCK SUFRESSORS/SUPPCRT	H12	ELECTRICAL CONDUCTORS
H6 A	Hangers	H12A	Bus
H6B	Supports		Control Cable
H6C	Stabilizers	H12B H12C	
H6D	Snubbers	H120	Power Cable
	51120021 5		Signal Cable
H7 CE	NERATORS	H12E	Thermocouple Extension Vire
	MERTICKS	111.2	CONTROL BODS
H7A	Alternator	H13	CONTROL RODS
	_	111 4	
H7B H7C	Converter	H14	HEATERS
H7D	Dynamotor Generator		
H7E	Amplidyne	H14A	Electric
H7Ē	Inverter	H14B	Fuel Gil
		H14C	Gas
H8 F U	EL ELEMENTS	H15	BICWERS
_			
н9 VE	SSELS	H15A	Compressor
		H15B	Gas Circulator
H9A	Reactor Vessel	H15C	
H9B	Pressurizer Vessel	H15D	Ventilator
H9C	Containment/Dryvell	H15E	Vacuum
	Pressure Suppression		-
		H16	HEAT EXCHANGERS
H10BA	TTERIES		· · · ·
		H16A	• •
H1 OA	Lead	H16B	
H1OB	Nickel Cadmium	H1 6C	
		H1/6D	
		H1'6E	
		H1,6F	
		H1'6G	
		H1 ₆ H	
		H16J	Reheater

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H17	CHARUE/DISCHARGE MACHINE
H18	DEMINERALIZERS
H18A	Anion
H18E	Mixed Bed
H180	Cation
H19	CONTROL ROD DRIVE MECHANISM
H20	PUMPS
H20A	Axial
H20B	Centrifugal
H20C	Diaphragm
H2OD	Gear
H20E	Reciprocating
H20F	Radial
H20G	Rotary
Н2ОН	Vane Type
H20J	Electromagnetic
нгок	Jet
H21	TRANSFORMER
H21A	Fover
H21B	Voltage
H21C	Current
H21D	
H21E	
H21F	
H21G	Power Step-Down
H22	ELECTRIC BCARDS/PANELS
H23	TUREINES
H23A	Condensing
H23B	Noncondensing
H23C	Combustion
H23D	Hydro
H23E	Air

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- 22 - H24	1 PIPE	S, FITTINGS
H24	1A O:	rific e/ Diaph ra g m
H24	B No	zzle/Safe End
H24	iC Ri	pture Diaphragm
H24	D St	traight Section
H24	ie t i	lermowell
H24	F Mi	vers
H24	ig Me	ters (Flow)
H25	FILTE	R/STRAINERS
H25	A Me	mbrane
H25	B Me	chanical Restriction
H25	C PC	rous Solid
H25	D Ch	emical
H25	- ••	avity
H25	F Ce	ntrifugal
H25	G E 1	ectrostatic
H25	H Se	lf-Clean
H25	J Dri	un .

H26 DIESEL-GENERATOR (SETS)

H26A	2-Stroke in Line
H26B	2-Stroke "V"
H26C	4-Stroke in Line
H26D	4-Stroke "V"
H26E	2-Stroke Radial
H26F	4-Stroke Radial

H27 SENGURS/INSTR. AND CONTROL

H27A	Vibration
H27B	Position
H27C	Pressure
H27D	Flow
H27E	Temperature
H27F	Level/Frequency
H27G	Neutronic
H27H	Nuclear (Radioprot.)

		- 23 -	
[28	MCTORS	H31	RECTIFIERS
:28A	Electric	H31A	Charger
:28B :28C	Hydraulic Pneumatic	H32	CONTAINMENT INTERN. STRUCTURE
29	VALVES	нзз	FUEL TRANSFERT DEVICE
:30	VALVE CPERATORS	H34	ACCUMULATORS
:30A	Electric Motor	H34A	Liquid Pressurized
:30B	Hydraulic	H34B	Liquid Unpressurized
:30C	Pneumat./Diaphragm/Cylinder	H34C	Gas
:30D	Solenoid		
:30E	Float	H35	AIR/GAS DRYERS
:30 F	Explosive		
:30G	Mechanical (Pressure)		

Comments

The categories SYSTEMS AND COMPONENTS AFFECTED are including rather detailed subclasses since this part of the taxonomy is intended to cover technical failures as well as human malfunctions. When backtracking to find the cause of an abnormal event, a technical failure may be identified and localised in terms of systems and components affected. If no technical fault is identified, we have a case of human malfunction and the categories then specify the physical contact/interface between the technical system and the human activity. It may be identified as the last technical item found when backtracking the cause of the event. Component identification is considered important for the analysis of malfunctions in test, calibration and maintenance, however, a very detailed classification not being necessary. Correlation/compatibility with other (international) classification systems should be emphasized, therefore, the ISPRA classifications developed/under development are adopted. These classifications are intended for use in the ISPRA Component Event Data Bank, see Mancini et al. 1979.

COMPONENTS: MODE OF FAILURE ΗM HM1 Demanded change of state is not achieved * HM1.1 won't open HM1.2 won't close HM1.3 neither opens nor closes/does not switch HM1.4 fails to start HM1.5 fails to stop HM1.6 fails to reach design specifications HM2 Change in conditions (state) HM2.1 Classification as for suddenness and degree: HM2.1.1 catastrophic failure HM2.1.2 incipient failure HM2.2 Classification as for observed state of the component: HM2.2.1 no output HM2.2.2 outside specifications ** HM2.2.3 operation without request HM2.2.4 erratic output (false, oscillating, instability, drifting etc.

- * The definitions are of general nature and have to be properly interpreted for the various items.
- Including failure of item part found and repaired during preventive maintenance.

Comments

The ISPRA classification is adopted, see Mancini et al. 1979.

Correlation/compatibility with other (international) classification systems should be emphasized, therefore, the ISPRA classifications developed/under development are adopted. These classifications are intended for use in the ISPRA Component Event Data Bank, see Mancini et al. 1979.

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HC	COMPONENTS: CAUSES OF FAILURE
HCA	Engineering
HCA1	engineering/design (hardware)
HCA2	engineering/design (proced./specificat.)
НСАЗ	other causes related to engineering
нсв	Nanufacturing (in workshop)
HCC	Installation/construction (in situ)
HCD	Plant operation
HCD1	personnel error
HCD2	incorrect procedure/instructions
HCE	Maintenance, Testing, Measuring
HCE1	personnel error
HCE2	incurrect procedure/instructions
HCF	Material incompatibility (unexpected)
HCG	Expected wear, aging, corrosion, erosion, distortion,
	abrasion
нсн	Abnormal service condition
HCL	Pullution
HCM	Failure caused by other plant devices, by associated
	devices, or by off-site influence.
HCN	Unknown
HCO	Others (NGC)
Comments	

Comments

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The ISPRA classification is adopted, see Mancini et al. 1979.

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COMPONENTS: ACTIONS TAKEN HA HA2.1 Corrective Action HA2.1.1 Corrective maintenance HA2.1.1.1 repair without disassembly HA2.1.1.2 repair with partial disassembly HA2.1.1.3 repair with total disassembly HA2.1.1.4 recalibration, reseal, repack HA2.1.1.5 adjust HA2.1.1.6 repair part(s) HA2.1.1.7 replace part(s) HA2.1.1.8 repair component HA2.1.1.9 replace component HA2.1.1.10 temporary repair HA2.1.1.11 temporary by-pass HA2.12 Modification/Redesign of component HA2.1.3 Modification of operation duty (a) HA2.1.4 Special surveillance (a) HA2.1.5 Control of similar equipment HA2.2 Administrative Consequences HA2.2.1 On Repair Schedule HA2.2.1.1. Urgent Repairs - urgent repairs that may result from emergencies and are accomplished bypassing normal administrative procedures - urgent repairs accomplished without bypassing normal administrative procedures HA2.2.1.2 Not-wrgent Repairs - accomplished at a scheduled time - accomplished at nearest shut-down HA2.2.2 On Plant Operation HA2.2.2.1 Forced stop required HA2.2.2.2 Stop required at short term - repair within 2 days - repair within 7 days - repair within 14 days - repair within 30 days HA2.2.2.3 No unscheduled unit shut-down required HA2.2.2.4 Others

HA2.2.3 Documentation - Failure reported to architect/engineer HA2.2.3.1 HA2.2.3.2 - Failure reported to NSSS vendor HA2.2.3.3 - Failure reported to consultant HA2.2.3.4 - Failure reported to component manufacturer HA2.2.3.5 - Failure analysis recommended HA2.2.3.6 - Failure analysis performed HA2.2.3.7 - Photographs were made HA2.2.3.8 - LER submitted HA2.2.3.9 - None of the above HA2.3 Start-up Restrictions HA2.3.1 - No restriction HA2.3.2 - Permission by licensing authorities HA2.3.3 - Request Licensee Revision

Comments

The ISPRA classification is adopted, see Mancini et al. 1979. It is identical with that used under the human factors category ACTIONS TAKEN: Other actions taken. - 28 -

- CONSEQUENCES OF THE EVENT G
- Consequent effect on system as stated in category: G1 SYSTEMS AND COMPONENTS AFFECTED G1.1 System inappropriately put into operation G1.2 Loss of system function G1.3 Degraded system function G1.4 Loss of redundancy: G1.4.1 Loss of 1 train G1.4.2 Loss of 2 trains G1.4.3 Loss of 3 trains G1.4.4 Loss of more than 3 trains G1.5 No significant effect on system G2 Consequent effect on reactor operation: G2.1 No significant effect G2.2 Delayed coupling G2.3 Partial standstill or power reduction G2.4 Turbine trip G2.5 Reactor shut-down (automatic/manual trip, forced shut-down) G2.6 Abnormal off-site releases G2.7 Abnormal radiation level in working area Comments

The purpose of this category is not to characterise the human malfunction but to indicate the efficiency of the various measures for stopping the propagation of the event chain initiated by the malfunction. The category is based upon that used by ISPRA with a few changes.

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J	PERSONNEL IDENTIFICATION
J1	Utility management
J2	Plant management
J3	Shift supervisors
J4	Licensed operators or senior operators
J5	Non-licensed operations personnel
J6	Roving operators
J7	Maintenance and repair personnel:
J7.1	Mechanical profession
J7.1	Electrical profession
J7.2	Electronics profession
J7.4	Chemical profession
J7.5	Profession not specified
J8	Health physics personnel
J9	Design and fabrication personnel
J10	Construction personnel
J11	Contractor and consultant personnel
J12	Other foreign personnel
J13	Other not covered above
J14	Not stated

Comments

This category is intended to represent information on the educational background and organisational relation of the person. Implicitly it characterises the actual work situation of the person during the event. K PERSONNEL LOCATION

K1 Central control rooms

K2 Other control room consoles

K3 Relay and terminal rooms

K4 Work on equipment in plant under normal conditions

K5 Work on equipment in radiologically controlled areas

K6 Workshop

K7 Office

K8 Outdoor

K9 Other location

K10 Not stated, not applicable

Comments

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This category represents a general characterisation of the work location during the occurrence of the malfunction.

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L1Design and design changes of equipmentL2Procedure design and modificationL3FabricationL4InstallationL5InspectionL6Operation:L6.1MonitoringL6.2Manual acts, maneuvers and other manual operationsL6.3Inventory controlL6.4Supervisory controlL7Test and calibration:L7.1Getting access to location for work (including getting permit)L7.2Preparation of equipment and toolsL7.3Execution of the actual test and calibration acti- vityL7.4Restoration, removal of tools etc.L8Maintenance and repair (modification etc.):L8.1Getting access to location for work (including getting permit)L8.2Preparation of equipment and toolsL8.3Execution of the actual maintenance activityL8.4Restoration, removal of tools etc.L9LogisticsL10Administration: recording, reporting etc.L11Management: resource allocation and supervisionL12Other not covered aboveL13Not stated, not applicable	L	PERSONMEL TASK
 L3 Fabrication L4 Installation L5 Inspection L6 Operation: L6.1 Monitoring L6.2 Manual acts, maneuvers and other manual operations L6.3 Inventory control L6.4 Supervisory control L7 Test and calibration: L7.1 Getting access to location for work (including getting permit) L7.2 Preparation of equipment and tools L7.3 Execution of the actual test and calibration activity L7.4 Restoration, removal of tools etc. L8 Maintenance and repair (modification etc.): L8.1 Getting access to location for work (including getting permit) L8.2 Preparation of equipment and tools L8.3 Execution of the actual maintenance activity L8.4 Restoration, removal of tools etc. L9 Logistics L10 Administration: recording, reporting etc. L11 Management: resource allocation and supervision L12 Other not covered above 	L1	Design and design changes of equipment
L4InstallationL5InspectionL6Operation:L6.1MonitoringL6.2Manual acts, maneuvers and other manual operationsL6.3Inventory controlL6.4Supervisory controlL7Test and calibration:L7.1Getting access to location for work (including getting permit)L7.2Preparation of equipment and toolsL7.3Execution of the actual test and calibration activityL7.4Restoration, removal of tools etc.L8Maintenance and repair (modification etc.):L8.1Getting access to location for work (including getting permit)L8.2Preparation of equipment and toolsL8.3Execution of the actual maintenance activityL8.4Restoration, removal of tools etc.L9LogisticsL10Administration: recording, reporting etc.L11Management: resource allocation and supervisionL12Other not covered above	L2	Procedure design and modification
 L5 Inspection L6 Operation: L6.1 Monitoring L6.2 Manual acts, maneuvers and other manual operations L6.3 Inventory control L6.4 Supervisory control L7 Test and calibration: L7.1 Getting access to location for work (including getting permit) L7.2 Preparation of equipment and tools L7.3 Execution of the actual test and calibration activity L7.4 Restoration, removal of tools etc. L8 Maintenance and repair (modification etc.): L8.1 Getting access to location for work (including getting permit) L8.2 Preparation of equipment and tools L8.3 Execution of the actual maintenance activity L8.4 Restoration, removal of tools etc. L9 Logistics L10 Administration: recording, reporting etc. L11 Management: resource allocation and supervision L12 Other not covered above 	L3	Fabrication
 L6 Operation: L6.1 Monitoring L6.2 Manual acts, maneuvers and other manual operations L6.3 Inventory control L6.4 Supervisory control L7 Test and calibration: L7.1 Getting access to location for work (including getting permit) L7.2 Preparation of equipment and tools L7.3 Execution of the actual test and calibration activity L7.4 Restoration, removal of tools etc. L8 Maintenance and repair (modification etc.): L8.1 Getting access to location for work (including getting permit) L8.2 Preparation of equipment and tools L8.3 Execution of the actual maintenance activity L8.4 Restoration, removal of tools etc. L9 Logistics L10 Administration: recording, reporting etc. L11 Management: resource allocation and supervision L12 Other not covered above 	L4	Installation
 L6.1 Monitoring L6.2 Manual acts, maneuvers and other manual operations L6.3 Inventory control L6.4 Supervisory control L7 Test and calibration: L7.1 Getting access to location for work (including getting permit) L7.2 Preparation of equipment and tools L7.3 Execution of the actual test and calibration activity L7.4 Restoration, removal of tools etc. L8 Maintenance and repair (modification etc.): L8.1 Getting access to location for work (including getting permit) L8.2 Preparation of equipment and tools L8.3 Execution of the actual maintenance activity L8.4 Restoration, removal of tools etc. L9 Logistics L10 Administration: recording, reporting etc. L11 Management: resource allocation and supervision L12 Other not covered above 	L5	Inspection
 L6.2 Manual acts, maneuvers and other manual operations L6.3 Inventory control L6.4 Supervisory control L7 Test and calibration: L7.1 Getting access to location for work (including getting permit) L7.2 Preparation of equipment and tools L7.3 Execution of the actual test and calibration activity L7.4 Restoration, removal of tools etc. L8 Maintenance and repair (modification etc.): L8.1 Getting access to location for work (including getting permit) L8.2 Preparation of equipment and tools L8.3 Execution of the actual maintenance activity L8.4 Restoration, removal of tools etc. L9 Logistics L10 Administration: recording, reporting etc. L11 Management: resource allocation and supervision L12 Other not covered above 	L6	Operation:
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 L9 Logistics L10 Administration: recording, reporting etc. L11 Management: resource allocation and supervision L12 Other not covered above 	L8.3	Execution of the actual maintenance activity
L10 Administration: recording, reporting etc. L11 Management: resource allocation and supervision L12 Other not covered above	L8.4	Restoration, removal of tools etc.
L11 Management: resource allocation and supervision L12 Other not covered above	L9	Logistics
L12 Other not covered above	L10	Administration: recording, reporting etc.
	L11	Management: resource allocation and supervision
L13 Not stated, not applicable	L12	Other not covered above
	L13	Not stated, not applicable

Comments

The identification of the task is important to describe the circumstances during which the event occurred. Description of elements and structure of a task and correlation with data on HUMAN MALFUNCTION MECHANISMS and INTERNAL HUMAN MALFUNCTIONS are necessary to predict human performance in new or revised work situations.

The tasks of Test/Calibration and Maintenance/Repair are described rather detailed in the present taxonomy, because they were well represented in the sample on which the taxonomy has been based control should be considered for extended description in actual data collection campaigns.

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- M EXTERNAL MODE OF MALFUNCTION AS LEADING TO THE STATED CONSEQUENCES OF THE EVENT
- M1 The specified or intended task not performed due to
- M1.1 Omission of task
- M1.2 Omission of act
- M1.3 Inappropriate, inaccurate performance
- M1.4 Inappropriate timing
- M1.5 Actions in wrong sequence
- M2 <u>The effect is due to specific, erroneous acts</u> on system under treatment:
- M2.1 Wrong act executed on correct component, equipment
- M2.2 Wrong component, equipment
- M2.3 Wrong time
- M3 The effect is due to extraneous act, i.e. act on other system than that under treatment
- M4 <u>The effect is due to coincidence</u> or co-effect with other erroneous or normal human activity or technical condition. Sneakpath tied to special circumstances

M5 <u>Not stated</u>, not applicable

Comments

This category describes the immediate, observable external effect of human malfunction upon the task performance. It reflects the way in which the malfunction initiates the consequent chain of accidental events. This category and the correlation to categories INTERNAL HUMAN MALFUNCTION and MECHANISMS OF HUMAN MALFUNC-TIONS, are important for prediction of the effect of human malfunction in a specific task and/or system. In case of simple human malfunction, there is found a direct

relation between these three categories and the structure of the task, in more complex situations involving a sequence of critical human decisions, this is not the case (see comment to INTERNAL HUMAN MALFUNCTION). Likewise, in some cases the effect cannot be predicted from a task analysis (extraneous acts). Therefore, special subcategories are given for extraneous acts and complex coincidences. It is recommended that the content of the category EXTERNAL MODE OF MALFUNCTION is extended by future data collection campaigns for important safety related tasks as for instance repair and test/calibration. This can be done by extending the present category or, as it has been done in this taxonomy, by differentiating the description of the task. See the category PERSONNEL TASK.

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N POTENTIAL FOR SELF-CORRECTION

N1	Lack of correction by the performing person himself
	due to:
N1.1	Malfunction not immediately observable
N1.2	Malfunction not immediately reversible
N2	Not stated, not applicable

Comments

Information on the detection of the malfunction is important, since it is tightly coupled to the initiation of an event report, and, therefore, may bias the data reported. For instance human malfunction which is immediately corrected will not release a report, and potential for operators' self-monitoring will be an important bias on the data.

A more elaborate description of the potential for self-correction will be important, but should be part of the background description of the task for which event data are collected, not a part of the event record. The present members of the category has been used to separate the two major bias factors during analysis of existing event compilations.

P	SITUATION	FACTORS

P1	Task characteristics, "preparedness
P1.1	Familiar task on schedule
P1.2	Familiar task on demand
P1.3	Unfamiliar task on schedule
P1.4	Unfamiliar task on demand
P1.5	Other not covered above
P1.6	Not stated, not applicable
P2	Physical environment
P2.1	Noise
P2.2	Uncomfortable temperature, humidity, pressure, smell
	etc.
P2.3	Light
P2.4	Radiation
P2.5	Other not covered above
P2.6	Not stated, not applicable
P3	Work time characteristics
P3.1	Day shift
P3.2	Night shift
P3.3	In beginning of shift
P3.4	In middle of shift
P3.5	In end of shift
P3.6	Not stated, not applicable

Comments

Information on factors related to the general work situation which will modify performance and probability of human malfunction is important. In the present context, the categories SITUATION FACTORS and PERFORMANCE SHAPING FACTORS are used to describe the more general work conditions, such as noise, temperature, workload, etc., and other factors which are generally affecting the state of an operator and which are not tied to a causal relation among events and acts, but rather contributing an overall modification of the performance. Physiological and psychological factors related to individuals are not recommended for inclusion into an event reporting scheme. Important SITUATION FACTORS are related to the "preparedness"

of the operator for the specific event. The taxonomy in this respect includes a distinction between familiar and unfamiliar task and between scheduled task and task on demand.

A <u>familiar task</u> is a task which is performed frequently enough to enable the person to perform it by know-how, i.e. without the need for special planning or modification of procedures. An <u>unfamiliar task</u> is a task which needs special planning or consideration of modification of procedures or normal work practise, or is so infrequent that use of preplanned written instructions is needed.

<u>On schedule</u> refers to the situation when special procedures are planned ahead or existing procedures can be studied and rehearsed, or the task is initiated by the operator according to a time schedule.

<u>On demand</u> represents the situation when planning has to be done concurrently with task performance and typically is based on the operators diagnosis and immediate decisions, i.e. the task is called for unexpectedly by the system, e.g. interfering with an already running task.

The distinction between SITUATION FACTORS and PERFORMANCE SHAPING FACTORS is made only to separate the information which can be recorded immediately by check lists from information which depend on human factors analysis, respectively.

Cuidelines for use of the subcategories under "Task characteristics" are presented in Pedersen et al. 1981. .

	HA	ACTIONS TAKEN
	HA1	In order to improve human functions:
	HA1.1	Reinforcement of instructions
	HA1.2	Revision of procedures and instructions
	HA1.3	Modification of equipment design
•	HA1.4	Modification of work planning
	HA1.5	Modification of work situation
	HA1.5	Modification of organisation
	HA1.7	-
		Retraining and rehearsal
	HA1.8	Redesign of training program
	HA1.9	Other not stated
	HA2	Other actions taken:
	HA2.1	Corrective Action
	HA2.1.1	Corrective maintenance
	HA2.1.1.1	repair without disassembly
	HA2.1.1.2	repair with partial disassembly
	HA2.1.1.3 HA2.1.1.4	repair with total disassembly recalibration, reseal, repack
	HA2.1.1.5	adjust
	HA2.1.1.6	repair part(s)
	HA2.1.1.7	replace part(s)
	HA2.1.1.8	repair component
	HA2.1.1.9	replace component
	HA2.1.1.10	temporary repair
	HA2.1.1.11 HA2.1.2	temporary by-pass Modification/Redesign of component
	HA2.1.3	Modification of operation duty (a)
	HA2.1.4	Special surveillance (a)
	HA2.1.5	Control of similar equipment
	HA2.2	Administrative Consequences
	HA2.2.1	On Repair Schedule
	HA2.2.1.1	Urgent Repairs
		- urgent repairs that may result from emergencies and are
		accomplished by passing normal administrative procedures - urgent repairs accomplished without by passing normal ad-
	T	ministrative procedures
	HA2.2.1.2	Not-urgent Repairs
	T	- accomplished at a scheduled time
	T	- accomplished at nearest shut-down
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HA2.2.2	On Plant Operation				
HA2.2.2.1					
HA2.2.2.2					
	- repair within 2 days				
	m m 7 m				
	- " " 14 "				
HA2.2.2.3	No unscheduled unit shut-down required				
HA2.2.2.4	Others				
HA2.2.3	Documentation				
HA2.2.3.1	- Failure reported to architect/engineer				
HA2.2.3.2					
HA2.2.3.3	•				
HA2.2.3.4					
HA2.2.3.5	— · · · · · · · · · · · · · · · · · · ·				
HA2.2.3.6	- Failure analysis performed				
HA2.2.3.7					
HA2.2.3.8	- LER submitted				
HA2.2.3.9	- None of the above				
HA2.3	Start-up Restrictions				
HA2.3.1	- No restriction				
HA2.3.2	- Permission by licensing authorities				
HA2.3.3	- Request Licensee Revision				

Comments

This is a category describing the actions taken in order to remedy the malfunction.

The first subcategory covers actions particularly aiming at improving human functions, the second covers other actions and is identical with the ISPRA classification already given under HA COMPONENTS: ACTIONS TAKEN. - 40 -

Q INTERNAL HUMAN MALFUNCTION

Beware: Internal human malfunction does not necessarily imply a failure or error on the part of the man.

- Q1 Detection: Operator does not respond to a demand.
- Q2 <u>Identification of system state</u>: Operator responds but misinterprets the system state.
- Q3 Decision:
- Q3.1 <u>Selection of goal</u>: Operator responds to properly identified system state, but aims at wrong goal (e.g. operation continuity instead of safety).
- Q3.2 <u>Selection of system target state</u>: Operator selects an improper system target state to pursue proper goal (e.g. he decreases power to 80% instead of shutdown).
- Q3.3 <u>Selection of task</u>: The operator selects a task, an activity which will not bring the plant to the intended target state.
- Q4 Action:
- Q4.1 <u>Procedure</u>: The sequence of actions performed is inappropriate or incorrectly coordinated for the task chosen.
- Q4.2 <u>Execution</u>: The physical activity related to the steps in the procedure is incorrect.
- Q4.3 <u>Communication</u>: Written or verbal messages are given incorrectly.
- Q5 Not stated, not applicable

Comments

The operator's task which is specified in the category PERSONNEL TASK in terms referring to the operational requirements of the plant will require some internal, mental data processing or decision function.

The category INTERNAL HUMAN MALFUNCTION is a causality-ordered sequence of human decision elements and is used to characterise that step/element in the decision sequence which was inappropriately performed or not performed at all due to a habitual bypass.

There is basically some ambiguity in this classification: Firstly, the description in terms of identification, decision and execution can be done at several levels of detail in the task description. It is intended that the use in event classification should be kept at a high level referring to the overall task description. A repair task can be taken as example: the diagnostic part of this task: to find the fault, should, if incorrectly performed, be classified as "identification of system state".

Alternatively, assume that the diagnosis has been correctly performed, that the repair man's proper intention of component replacement has been stated, and that he is performing the actions necessary for the fault remedy. During this phase of activities the repair man performs actions in wrong order of succession, because he does not identify the real state of the system under repair: this should be classified as "procedure".

This is a matter of convention - but the position taken here can be defended, partly from the fact that information for classification at a very detailed level generally is not present in event reports, partly from the usefulness of the classification results for improvement of work aids.

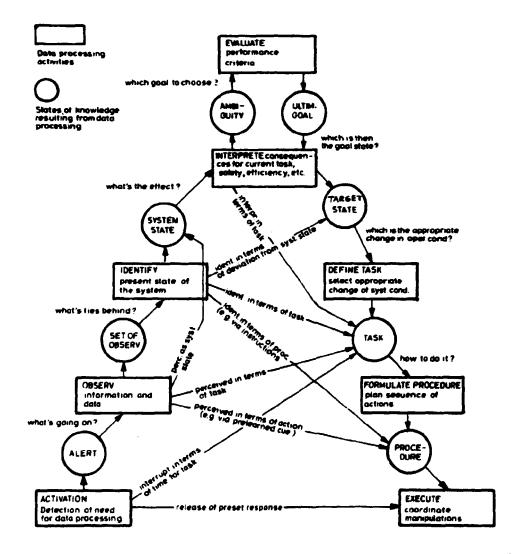
Secondly, ambiguity is caused by the fact that malfunction in the first phases of a decision will frequently lead to inappropriate decisions later in the sequence. To describe such sequences, detailed time line analysis and identification of all critical decisions are necessary, as described by Pew et al (1981), but this analysis must be based on very careful data collection including interviews of personnel (which is only feasible if it can be done immediately after the event, for instance by studies on training simulators.)

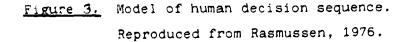
In general, the information cannot be obtained and in the present taxonomy we suggest that classification is only done for the <u>first</u> element of the human decision sequence which is inappropriately performed or shunted out by stereotyped bypass. Since most event reports are backtracking the course of events to an explaining plausible cause, this first malfunction sending the operator off the proper track, is the most likely to be represented in the record. This means that in more complex situations, the causal relation from the internal human malfunction and the related error mechanisms to the external effect of the malfunction will not be preserved in the recorded data. However, from a view point of statistical quantification or generalization. in terms of improvements, this is not too important in the present context since the variability and degrees of freedom in human responses after a wrong decision - say an identification - is so high that they can only be characterized after detailed studies.

It must be emphasized that the category INTERNAL HUMAN MALFUNCTION does not take into account any cause of the malfunction and that the term "malfunction" does not imply in itself a "human error".

The malfunction can be caused by external conditions or events, such as interfering people, wrong orders, ordered absence etc., which are all considered separately under CAUSES.

The members of the present category are derived from a model of human decision sequence which is described in detail in Rasmussen (1974) and which has been used to derive the guidelines for analysis presented in Pedersen et al. 1981. For reference the model is illustrated in Figure 3.





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CAUSES OF HUMAN MALFUNCTION

Event or short term condition taking active part as a link in the causal chain of events

R1 External events:

R

R1.1 Distraction by system and/or environment

- R1.2 Distraction by other persons: Questions, message, noise
- R2 Excessive task demand in the specific situation:
- R2.1 Physical demand, time, force, etc.
- R2.2 State information inadequate, wrong
- R2.3 Background information related to the specific situation (knowledge, instruction) inadequate or wrong
- R3 <u>Operator incapacitated</u>: (sick, injured, etc.)
- R4 No external cause:
- R4.1 Intrinsic normal human variability; spontaneous human error
- R4.2 Intentional act
- R4.3 Sabotage
- R5 <u>Other not stated above</u>
- R6 Not stated, not applicable

Comments

Identification of possible external causes is important for many reasons. First of all, there is a natural tendency when analysing the chain of events implied in maloperation of a system to accept a human error as the explanation if an inappropriate human act is met by the causal backtracking; the tendency is natural since it is difficult to continue the causal backtracking "through" a human performance, and also it is generally accepted that it is "human to err". It is, therefore, important that special care is taken to identify possible external causes as part of an event analysis.

Common sense definition of causes is very ambiguous and, therefore, in the present context must be clarified. From a point of view of quantification of human error it is beneficial if the definition of cause is clearly related to the frequency of the events analysed. Therefore, we define as a cause an event or a change in the man's normal work condition which acts as a causal precedent to his inappropriate 'action. General conditions which may affect his error proneness such as normal, but high noise level, inappropriate ergonomic design, fatigue during night shifts etc., are all considered SITUATION FACTORS or PERFOR-MANCE SHAPING FACTORS which influence the error probability, but - according to our definition - does not cause errors. The present members of the category "causes" should be taken as illustrative; they are based on a limited number of analyses, generally reliable information on causes is not to be found in event reports due to the reasons discussed above. Special guidelines for identification of causes as part of event analysis will be developed within the present CSNI work, based on the analysis published by Griffon (1981). More general guidelines for use of the category R: CAUSES OF

HUMAN MALFUNCTION are presented in Pedersen et al. 1981.

- S MECHANISMS OF HUMAN MALFUNCTION
- S1 Discrimination

This group is related to the man's ability to discriminate between and select the proper mode of control of his activities. The subcategories of malfunction mechanisms are characterized by interference between the man's repertoire of stereotyped habitual - and often subconscious - responses on one side and on the other side aspects of the actual work situation during infrequent and unique task demands.

S1.1

<u>Stereotype (skill) fixation</u>

Definition: Man operates in skill-based domain. He does not recognize a situation calling for attention and caution.

(Cues for recognition may not be present or may be overlooked, this is characterized by the categories: CAUSE OF HUMAN MALFUNCTION, or INTERNAL HUMAN MALFUNCTION)

S1.2 Familiar association short-cut

Definition: It is recognized that conscious identification of the situation is needed but familiar cues activate incorrect intention and task in man. It is not recognized that knowledge based evaluation and planning is needed.

S1.3 <u>Stereotype take-over</u>

Definition: Task or act according to proper intention, but "absentmindedness" during performance leads to relapse to stereotype action links related to different act or task.

- S1.4 Lack of recognition of familiar pattern Definition: Familiar pattern relevant for the situation is not recognised, higher level knowledge--based evaluation or planning is unnecessarily and inappropriately applied.
- S2 <u>Input information processing</u> The subcategories are related to the man's activities in obtaining information. That an information output malfunction has occurred is classified under:

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	INTERNAL HUMAN MALFUNCTION
	Erroneous function in action
	Communication given incorrectly
S2.1	Information not recieved/sought
	Definition: Cues do not activate man because sensi-
	tivity/attention is insufficient for present infor-
	mation level.
S2.2	Misinterpretation of information
	Definition: Response is based on wrong apprehension
	of information such as misreading of text or instru-
	ment, misunderstanding of verbal message.
\$2.3	Assumptions replace search for information
	Definition: Response is inappropriately based
	on information supplied by the operator (by recall,
	guesses, etc.) which does not correspond with
	information available from outside.
S 3	Recall
\$3.1	Forgetting isolated act or function
	Definition: Operator forgets to perform an isolated
	act or function, i.e., an act or function which
	is not cued by the functional context or is not
	having immediate effect upon the mental or motor
	sequence.
\$3.2	Mistake among alternatives
	Definition: Simple choice of wrong alternative,
	a category is correctly used but by wrong member,
	e.g., mistakes of up/down, +/-, left/right, A/B,
	open/closed, locked/unlocked.
\$3.3	Other slips of memory
	Definition: Erroneous recall of reference data
	values; names, item; need for actions, etc.
	Inferences
	This group is covering problems of linear thought
~ /	in causal nets.
54	Side effects or latent conditions not adequately
•	considered
	Definition: The man is in a less familiar situation
	characterized by knowledge-based, goal-controlled
	performance. He performs erroneously during func-

tional inferences: The situation is not properly identified, the consequences of an event chain are not adequately predicted or an improper intention is chosen or latent conditions are not adequately considered. Consequently, the task or the intended goal is not fulfilled or adverse side effects occur or a combination of these consequences. (Can be due to oversight, lack of knowledge etc., this is characterized by the category: CAUSE OF HUMAN MALFUNCTION.

S5 Physical coordination

S5.1

Motor variability

Definition: Lack of manual precision, too big/small force applied, inappropriate timing. Including deviations from "good craftsmanship".

S5.2 <u>Topographic, spatial orientation inadequate</u> Definition: In spite of man's correct intention and his correct recall of identification marks, tagging etc., he unawaringly performs task/act in the wrong place or on the wrong object, because he is following his immediate sense of locality, this, however, not being applicable (not updated, surviving imprints of old habits etc.).

S6 Other identified mechanisms

S7 <u>Mechanism not identified</u>

Comments

This category represents an attempt to formulate a set of generic, task independent human error mechanisms. The related categories EXTERNAL MODE OF MALFUNCTION and INTERNAL HUMAN MALFUNCTION are tightly task related and reflect basically the effect of inappropriate human performance upon the task. To evaluate human performance during design of new tasks and improved work conditions, including man-machine interfaces, it is important to identify human malfunction mechanisms in generic terms relating inappropriate task performance to features of the psychological mechanisms which are the basis of the performance and to limiting properties of such mechanisms.

A human is capable of performing the same task in various different ways depending upon the state of training, the subjective formulation of the goals and performance criteria, and consequently the role of the psychological mechanisms will be very person and situation dependent. Inappropriate task performance reflects a mismatch between task requirements and the human resources applied, and if the nature of this mismatch can be identified - irrespectively of the underlying cause - important information on the psychological mechanism applied and its limiting properties with respect to the task can be obtained.

The present category is intended to characterize cases of such resource/demand mismatch and is based on a model of operator performance derived from a preliminary analysis of 200 event reports (Rasmussen 1980). The structure of the model is illustrated in figure 4.

Guidelines for use of the category S: MECHANISMS OF HUMAN MAL-FUNCTIONS are presented in Pedersen et al 1981.

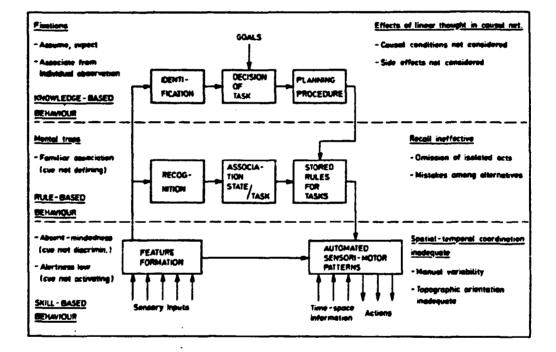


Figure 4, Model of human data processes and typical malfunctions. Reproduced from Rasmussen, 1980.

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Т	PERFORMANCE SHAPING FACTORS
T1	Subjective goals and intentions:
T1.1	Aspects of task performance are given exaggerated
	promotion e.g., speed, thoroughness, accuracy,
	effort to avoid delay
T1.2	Task content is inappropriately extended
T1.3	Task perceived as secondary
T1.4	Conflicting goals
T1.5	Other not covered above
T1.6	Subcategory not applicable
Т2	Mental load, resources:
T2.1	Inadequate ergonomic design of work place
T2.2	Overlapping tasks
T2.3	Inadequate general education
T2.4	Inadequate general task training and instruction
T2.5	Other not covered above
T2.6	Subcategory not applicable
ТЗ	Affective factors:
T3.1	Social factors
ТЗ.2	Insufficient load, boredom
T3.3	Time pressure
T3.4	Fear of failure
T3.5	Other not covered above
ТЗ.6	Subcategory not applicable

Comments

See comments to SITUATION FACTORS.

Guidelines for identifying performance shaping factors will be developed, based on the analysis in Griffon (1981). Guidelines for use of the subcategories under "Mental load, resources" are presented in Pedersen et al 1981.

DATA COLLECTION FORMATS

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Preprinted forms for data collection in plant and examples of their use are presented in the document SINDOC(81)15.

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Title and author(s)	Date March 1981
Classification System for Reporting Events Involving Human Malfunctions	Department or group
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	SINDOC(81)14 R-6-80
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The report describes a set of categories for reporting industrial incidents and events involving human malfunction. The classifi- cation system aims at ensuring information adequate for improvement of human work situ- ations and man-machine interface systems and for attempts to quantify "human error" rates. The classification system has a multifacetted non-hierarchical structure and its compati- bility with Ispra's ERDS classification is described. The collection of the information in general and for quantification purposes are discussed. 24 categories, 12 of which being human factors oriented, are listed with their respective subcategories, and comments are given. Underlying models of human data processes and their typical malfunctions and of a humar	
<pre>decision sequence are described. 7 references. Available on request from Risø Library, Risø National Laboratory (Risø Bibliotek), Forsøgsanlæg Risø), DK-4000 Roskilde, Denmark Telephone: (03) 37 12 12, ext. 2262. Telex: 43116</pre>	

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